

http://en.keyes-robot.com http://keyes-robot.taobao.com

Openwrt WiFi Smart Car Wireless Video Transmission Module

Module: MB0076

Keyes Rt5350 open wirte wifi video module usage information

Step 1: Start the SSH client. The firmware of the default brush IP is 192.168.1.100 Login name: root Password: admin



Step 2: Log in to the interface

P 192.168.1.150 - PuTTY	
I I	
Robot-Link V3.0 Base on OpenWrt www.xiao-r.com root@Robot-Link:~# root@Robot-Link:~# root@Robot-Link:~# root@Robot-Link:~# root@Robot-Link:~#	-



Step 4: Is instructions to view the contents of the file and copy the command line

🚱 192.168.1.150 - PuTTY	
jpg_streamer -i "input_uvc.so -r 320x240 -f 20 -yuv" -o "output_http.so -p 8090"	-
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- zzl 1/2 50%	-



Step 6: Connect the USB camera after Is / dev/

P 192.168.1.150 - PuTT	TY			
root@Robot-Link:~	1s /dev/			
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console	mtd2	mtdblock2	random	
cpu dma latency	mtd2ro	mtdblock3	shm	
full	mtd3	mtdblock4	tty	
kmag	mtd3ro	mtdblock5	ttyS0	
Log	mtd4	network latency	ttyS1	
500	mtd4ro	network throughput	urandom	
atd0	mtd5	null	watchdog	
td0ro	mtd5ro	ppp	watchdog0	
atd1	mtdblock0	ptmx	zero	
coot@Robot-Link:~	# 1s /dev/			
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itd0ro	mtdblock0	pta		
atd1	atdblock1	random		
tdiro	mtdblock2			
root@Robot-Link:~	+			

Step 7: Paste the copied instructions in the document

192.168.1.150 - PuTTY	_	-	_	_		- 0 X
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UVCIOC CIRL ADD - E	rror: inappropriate :	loctl for	device			
Adding control for	Tilt Reset					
UVCIOC CIRL ADD - E	rror: inappropriate .	locti for	device			
Adding control for	Pan/tilt Reset					
UVCIOC_CIRL_ADD - E	rror: Inappropriate	loctl for	device			
Adding control for	focus (absolute)					
OVCIOC CIRL ADD - E	rror: inappropriate .	loctl for	device			
mapping control for	Pan (relative)					
UVCIOC CIRL MAP - E	rror: Inappropriate .	loctl for	device			
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Step 8:

Open the PC monitoring software and enter the system configuration options. Configuration Control address and video address 192.168.1.150 The corresponding address is also this address. The address of the module we normally sell is 192.168.1.100

😥 WIFI/蓝牙	牙智能小车操纵平台PO	C正式版V2.0 by li	uviking 中国FPV-WIFI机器	人网·机器人创意工作	乍室出品 论坛:www.wifi	-robots.com 引擎版本:V2R05	X
平台操作	控制模式 视频效	水果 辅助功能	帮助				
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				WiFi参数设置			
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		视频地址2]	http://192.168.1.150:8081	/?action=stream			
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	控制權	莧式:未选择	小R科技	有限公司(www.xiao	-r.com) 旗下 WIFI机器人网	网·机器人创意工作室版权所有	

Step 9:

Log in to the interface to select the control mode wifi control, whether it is wifi wireless connection also This mode can be selected for the network cable connection, and then video monitoring is enabled.



Step 10: Finally end the video monitoring at the command line terminal Ctrl + C

