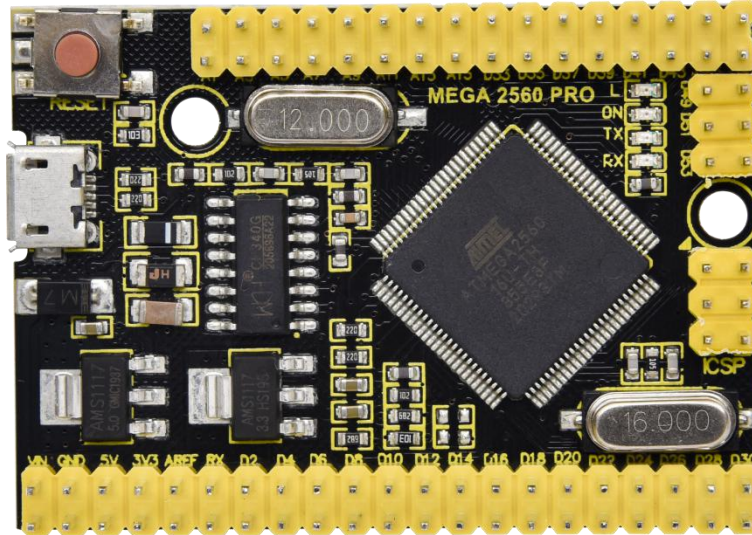




Keyestudio MEGA 2560 PRO Development Board (Black and Eco-friendly)



Contents

1. Introduction.....	2
2. Specification.....	3
3. Pin Interfaces:.....	4
4. Windows System.....	8
4.1 Download Arduino IDE.....	8
4.2 Installing Driver.....	10
4.3 Arduino IDE Setting.....	14
5.4 Start A Program.....	20
5. MAC System.....	24
5.1 Install Arduino IDE on MAC System.....	24



5.2 Download the Driver of CH340.....	25
5.3 How to Install the Driver of CH340.....	25
5.4 Arduino IDE Setting.....	25

1. Introduction

The mega 2560 control board, among the series of MCUs , is the most popular since it has numerous pins.

However, a substantial number of pins don' t meet the space demand of DIY design. To tackle this issue, we roll out the Keyestudio MEGA 2560 PRO development board. In fact, its use method is as same as the official mega board, in addition to the different volume.

Its processor core is ATMEGA2560-16AU. In the meantime, it has 54 digital input/output pins (of which 15 can be used as PWM outputs), 16 analog inputs, 4 channel serial communication ports, a USB connection, 1 ICSP header, and a reset button. And all ports are extended by pins with the interval of 2.54mm.

What's more, you can burn the firmware for ATMEGA2560-16AU through the built-in ICSP port. The firmware of this chip is burnt well before delivery, therefore, you don't need to burn the firmware.



The power can be supplied through USB cable, port 5V , GND (DC 5V) , as well as Vin GND (DC 7-12V).

2. Specification

Microcontroller: ATMEGA2560-16AU

USB to serial chip: CH340G

Operating Voltage: 5V

Input Voltage (recommended):DC 7-12V

Digital I/O Pins: 54 (D0-D53)

PWM Digital I/O Pins: 15(D2-D13 D44-D46)

Analog Input Pins: 16(A0-A15)

DC Current per I/O Pin: 20 mA

DC Current for 3.3V Pin: 50 mA

Flash Memory: 256 KB of which 8 KB used by bootloader

SRAM: 8 KB

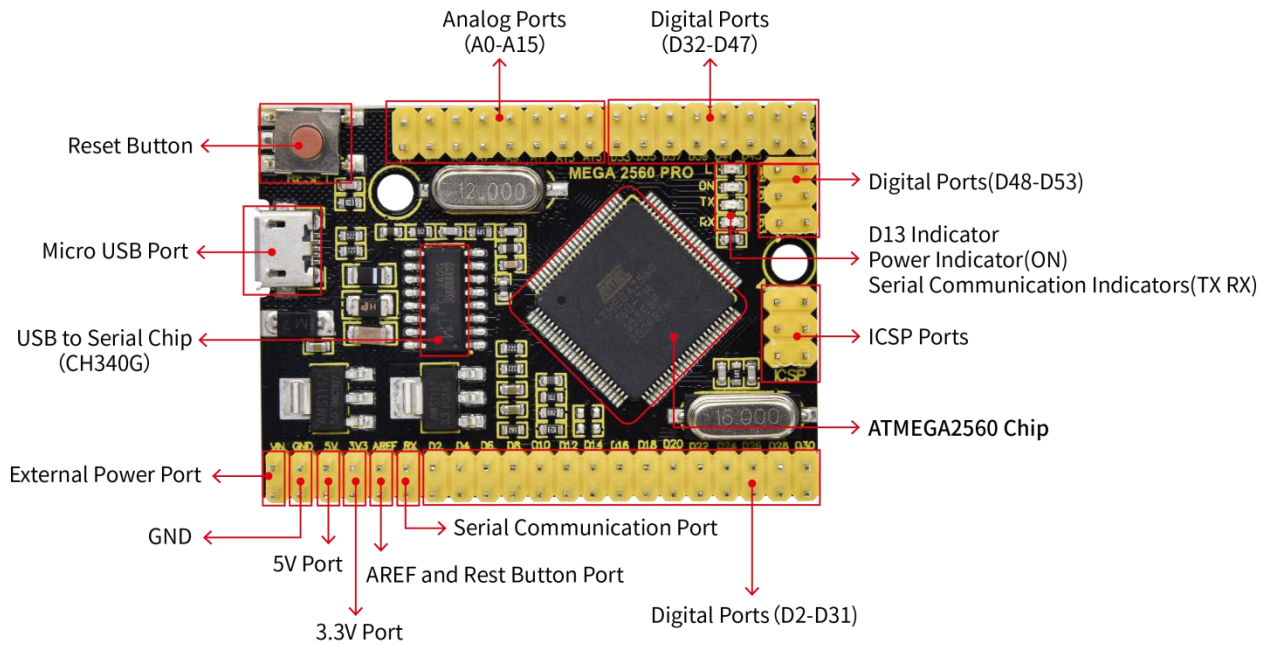
EEPROM: 4 KB

Clock Speed: 16 MHz



LED_BUILTIN:D13

3. Pin Interfaces:



1	External Power Ports	External input: DC 7-12V
2	Ground	GND
3	5V	DC 5V input/output voltage (supply power for control board when inputting 5V)



4	3.3V	Provide DC 3.3V output voltage
5	AREF	Analog reference. Used to set the external reference voltage(0-5V)
6	Reset Button Port	Can be connected to press button, as same as reset button
7	Serial communication port	The default serial communication port, RX responds to D0 (digital port), TX responds to D1 (digital port)
8	Digital Ports	Have 54 digital input/output pins (of which 15 can be used as PWM outputs). These pins can be configured as digital input pin to read the logic value (0 or 1). Or used as digital output pin to drive different modules like LED, relay, etc.
9	Analog Ports	16 analog pins (A0-A15)
10	ATMEGA 2560 (Microc	Each board has its own microcontroller,. The MCU of this board is ATMEGA2560-16AU.



	ontroller)	
11	ICSP Pin	<p>the AVR, an Arduino micro-program header consisting of MOSI, MISO, SCK, RESET, VCC, and GND.</p> <p>It is often called the SPI (serial peripheral interface) and can be considered an "extension" of the output. In fact, slave the output devices to the SPI bus host.</p> <p>When connecting to PC, program the firmware to ATMEGA2560-16AU.</p>
12	L Indicator	When D13 is high level, LED will be on; when it is low level, LED will be off
13	ON Indicator	LED is on when control board is plugged in power, otherwise, it will be off
14	TX Indicator	When Arduino board communicates via serial port and sends the message, TX led will flash
15	RX Indicator	When Arduino board communicates via serial port and receive the message, RX led will flash.
16	Reset Button	Reset your control board
17	Micro USB	Supply power for control board and upload code
18	USB to	CH340G, transform USB signals of computer to



	serial chip	serial signals
--	----------------	----------------

3. Specialized Functions of Some Pins:

Serial Communication Port(4-channel): Serial (D0 corresponds to RX0, D1 is equivalent to TX0) , Serial1 (D19 corresponds RX1, D18 is equivalent to TX1), Serial2 (D17 corresponds to RX2, D16 stands for TX2) and Serial3 (D15 stands for RX3, D14 corresponds to TX3) .

RX (D0) and TX (D1) are connected to the USB to serial chip of CH340G

- **Serial Communication:** D0 (RX0) and D1 (TX1); Serial 1: D19 (RX1) and D18 (TX1); Serial 2: D17 (RX2) and D16 (TX2); Serial 3: D15 (RX3) and D14 (TX3).
- **PWM Pins (Pulse-Width Modulation):** D2 to D13, and D44 to D46.
- **External Interrupts:** D2 (interrupt 0), D3 (interrupt 1), D18 (interrupt 5), D19 (interrupt 4), D20 (interrupt 3), and D21 (interrupt 2).
- **SPI communication:** D53 (SS), D52 (SCK), D51 (MOSI), D50 (MISO).
- **IIC communication:** D20 (SDA); D21 (SCL).



4. Windows System

4.1 Download Arduino IDE

When getting this control board, we need to install Arduino IDE

Enter the website <https://www.arduino.cc/>, and click  > 



You can select the latest version-----1.8.13. Alternatively, the previous release is your another choice.

In this project, we use 1.8.12 version.



Previous Releases

Download the previous version of the current release, the classic 1.0.x, or old beta releases.

DOWNLOAD OPTIONS

Previous Release (1.8.12)

Arduino 1.0.x

Arduino 1.5.x beta

Arduino 1.9.x beta

Click **Previous Release (1.8.12)** to enter the new page. As shown below;

The **Windows installer** needs installing manually. Yet , the **Windows zip file for non admin install**, a zip file of Arduino 1.8.12 version, can be directly downloaded and installed.



Previous IDE Releases

ARDUINO 1.8.12

Arduino IDE that can be used with any Arduino board, including the Arduino Yún and Arduino DUE. Refer to the [Getting Started](#) page for Installation instructions.

[See the release notes.](#)

Windows Installer

Windows ZIP file for non admin install

Mac OS X 10.8 Mountain Lion or newer

Linux 32 bits

Linux 64 bits

Linux ARM 32

Linux ARM 64

Source

4.2 Installing Driver

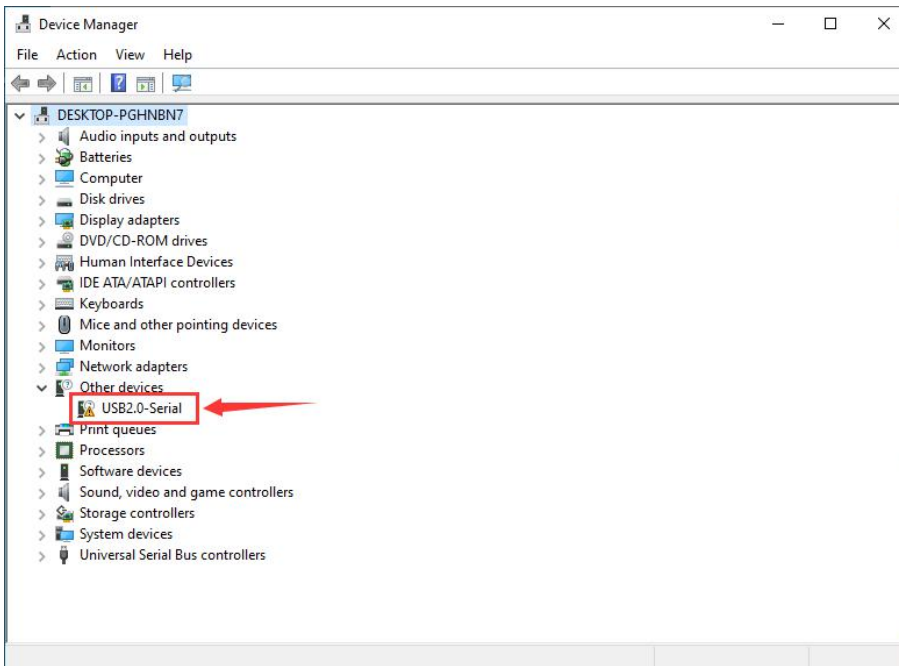
For this part, we need to install the driver of Arduino IDE

First, let' s attach USB cable to computer. The driver can be installed automatically if the PC system is Windows 10, however, you need to install the driver manually if the PC system is other version.

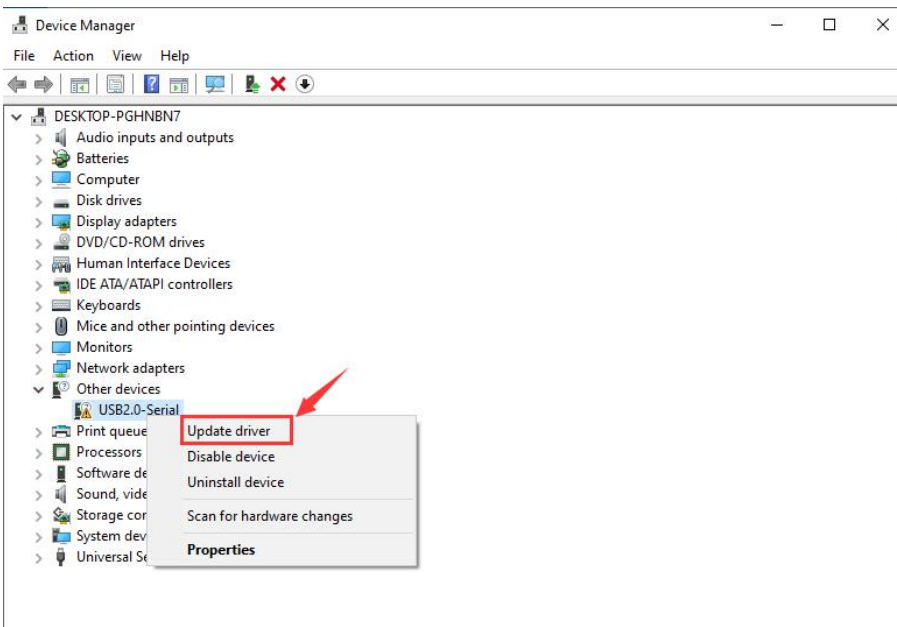
The USB to serial chip of control board is CH340G, therefore, we will install its driver(usb_ch341_3.1.2009.06).



Click Computer----- Properties----- Device Manager, as shown below:



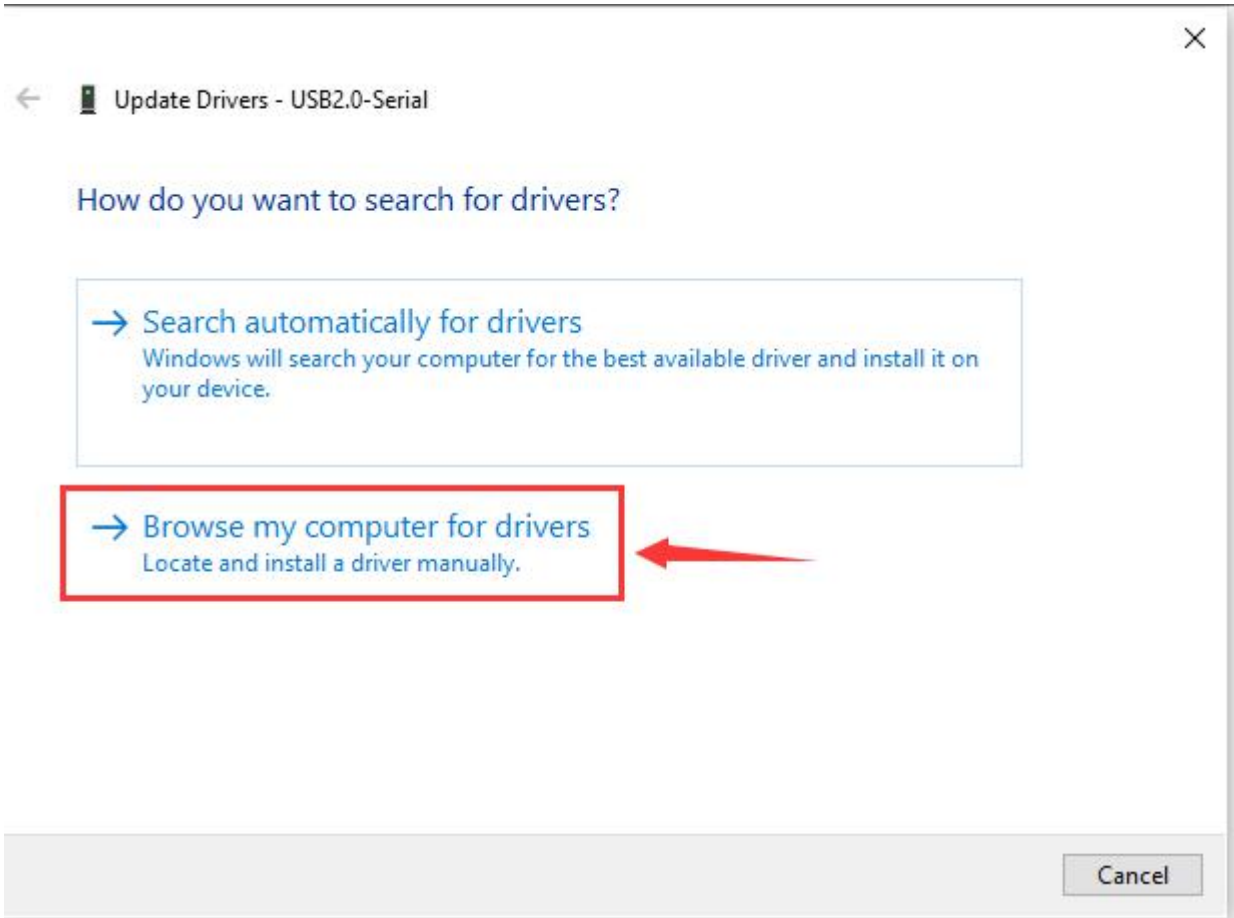
Click  USB Serial and "Update Driver Program"



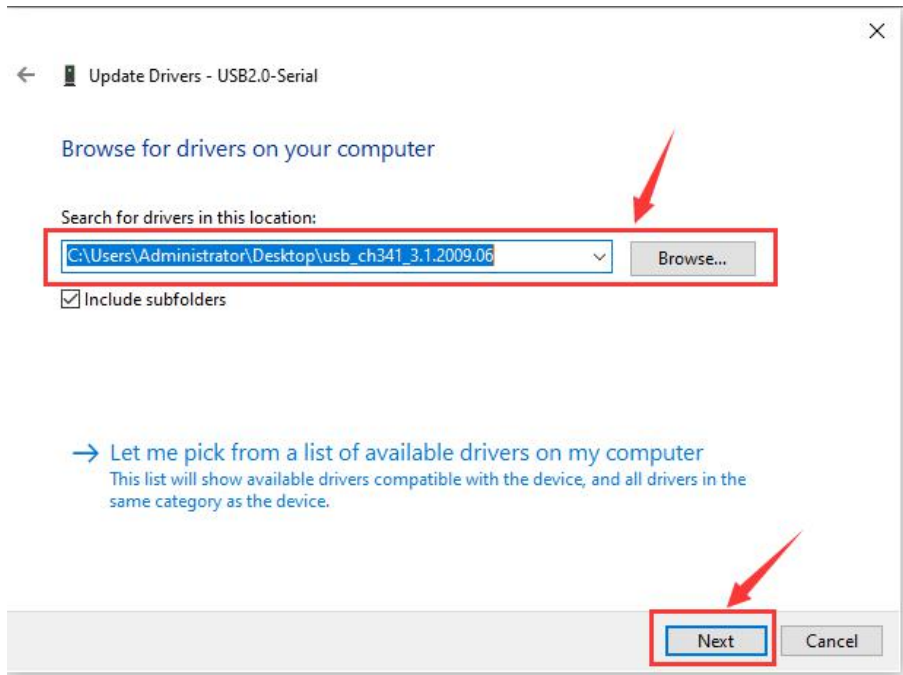
Jump into the following page and select "Browse my computer for driver"



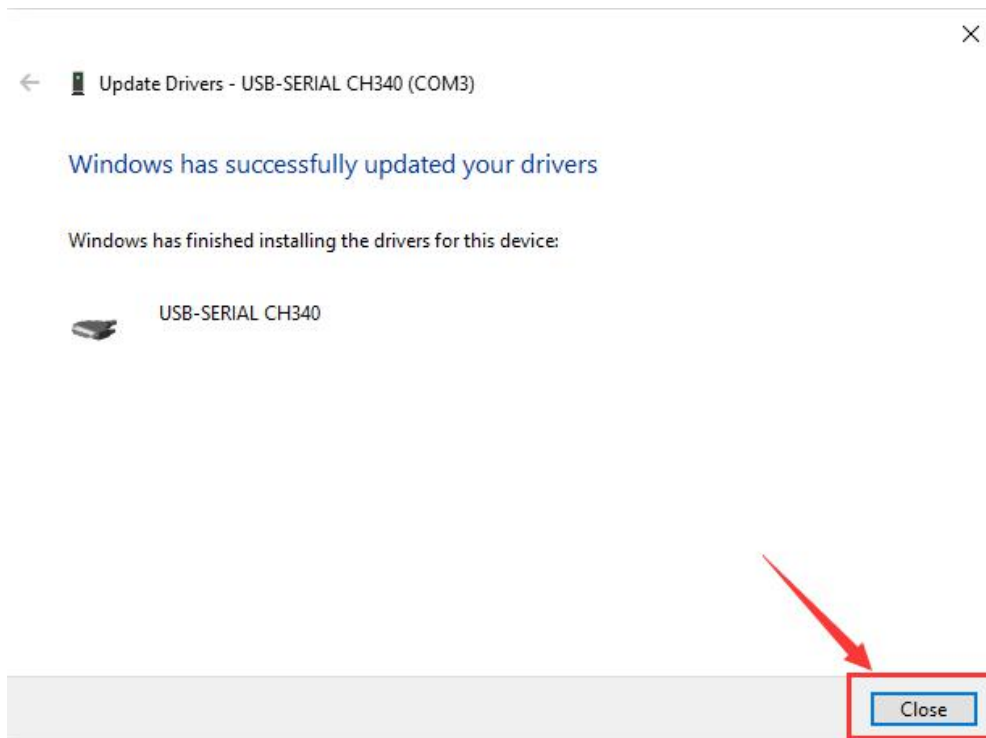
software” .



Search the **usb_ch341_3.1.2009.06** folder

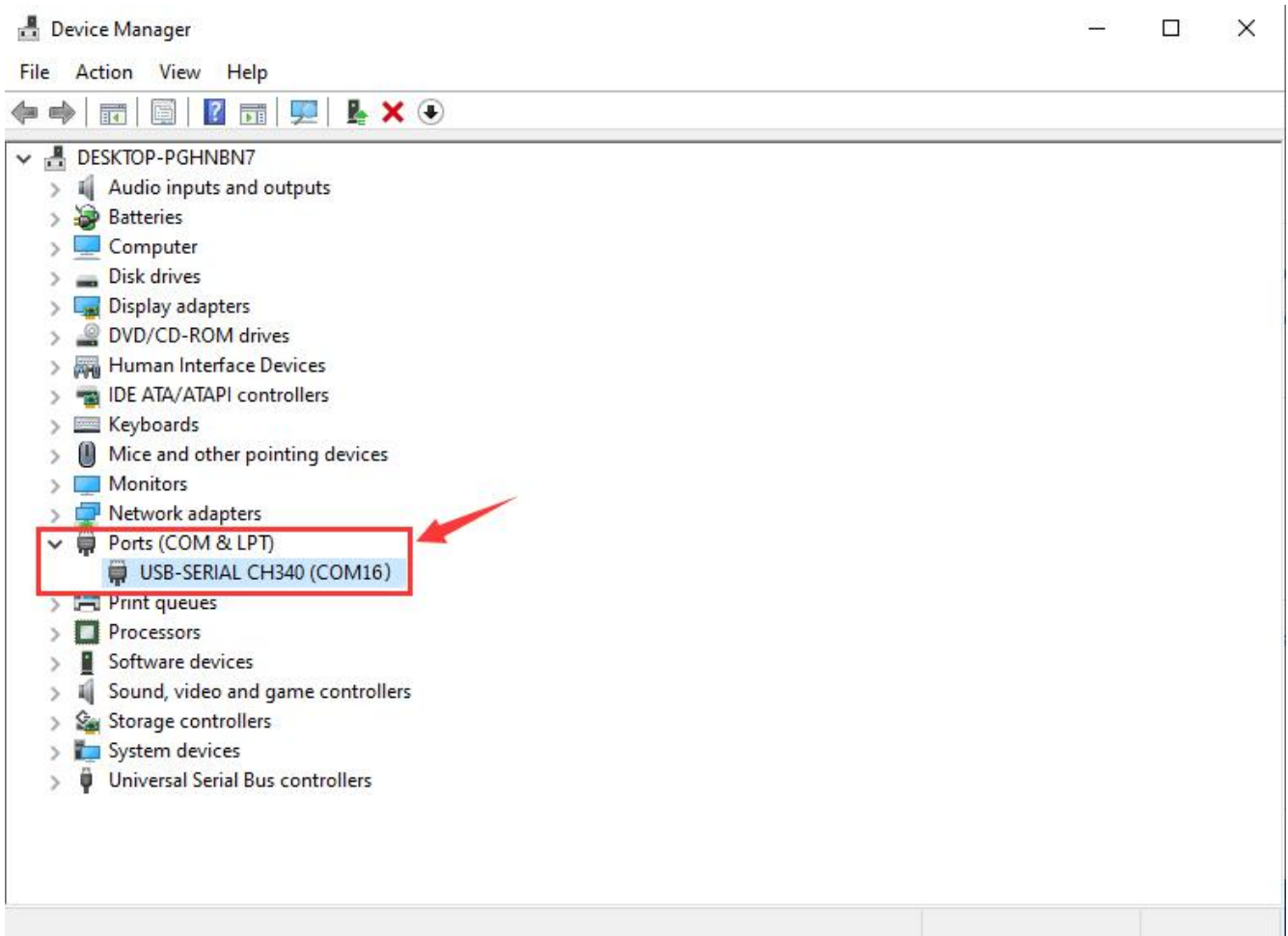


After the driver is installed, you need to click **Close**.





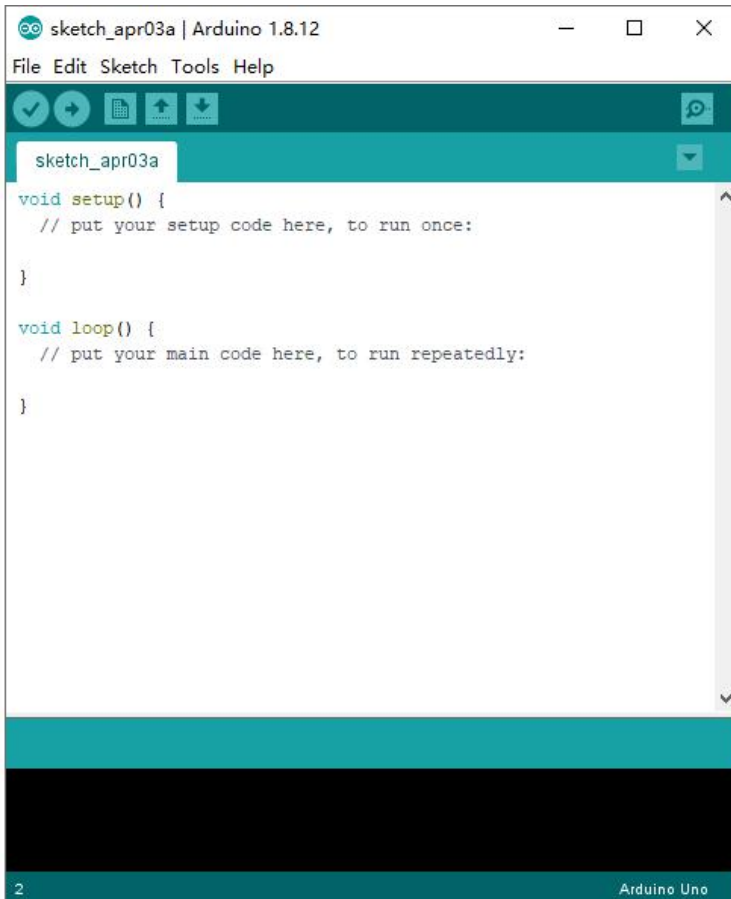
Click Computer----- Properties----- Device Manager, as shown below



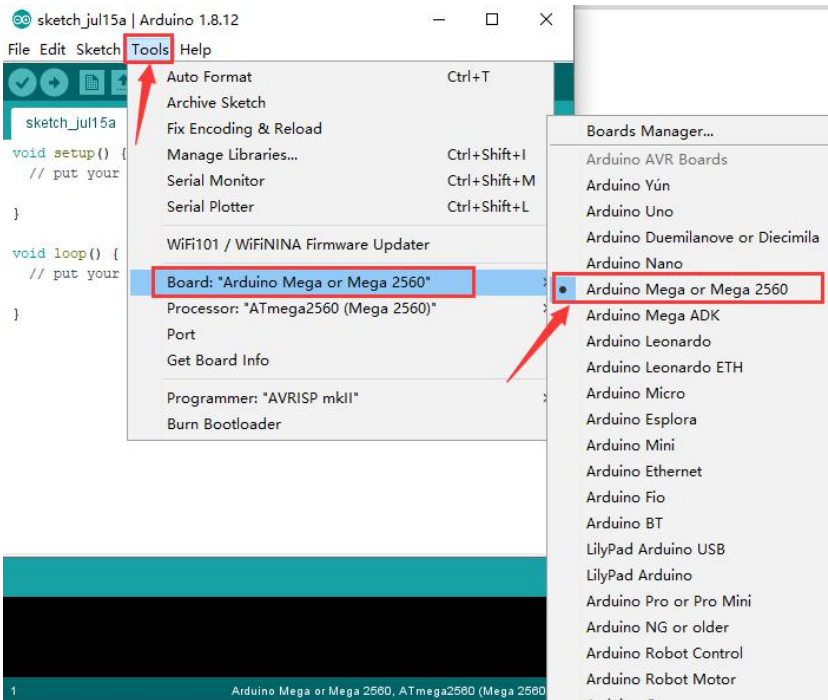
4.3 Arduino IDE Setting



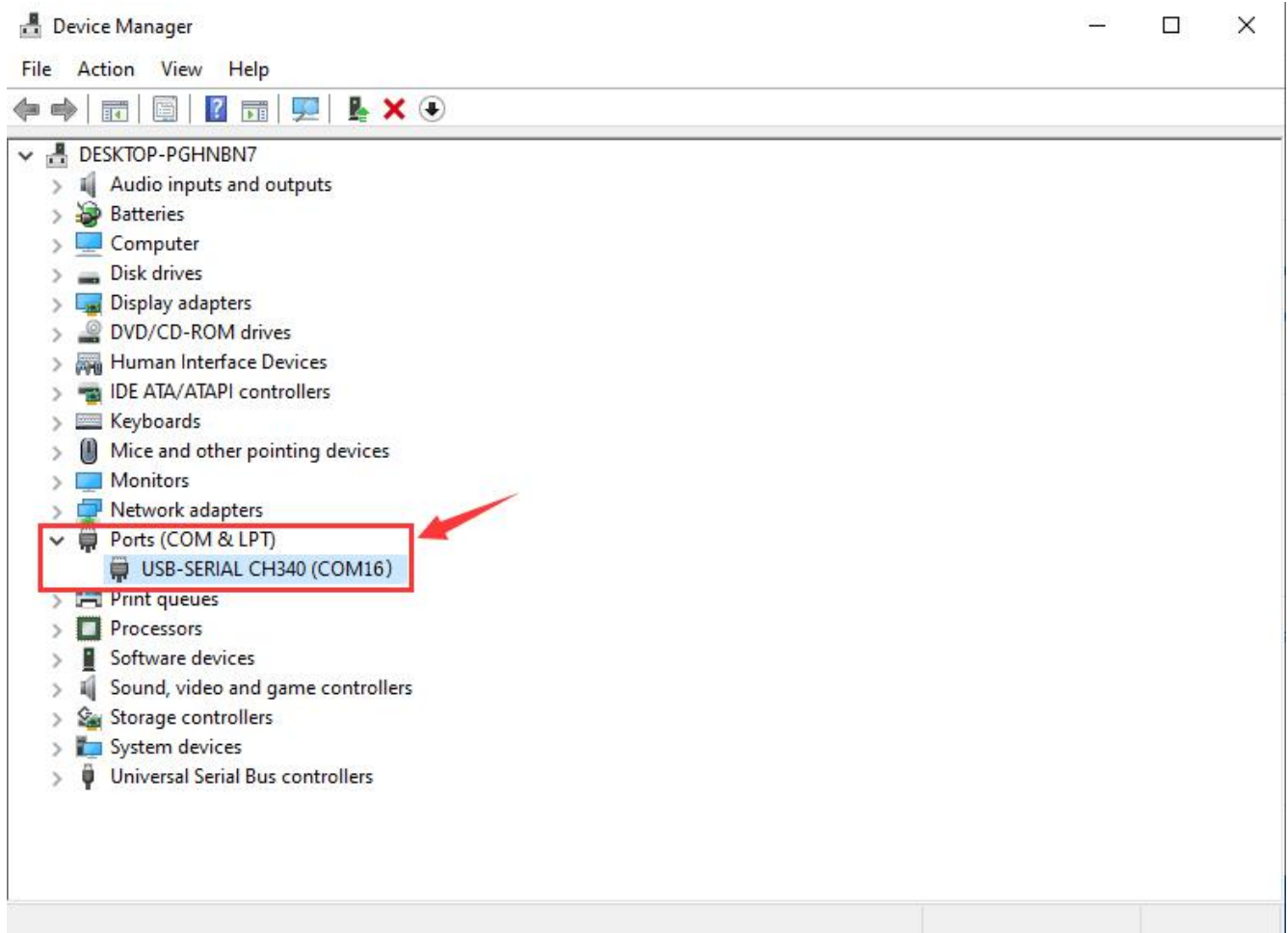
Click  icon to pen Arduino IDE.



When downloading the sketch to the board, you must select the correct name of Arduino board that matches the board connected to your computer. As shown below;



Then select the correct COM port (you can see the corresponding COM port after the driver is successfully installed).



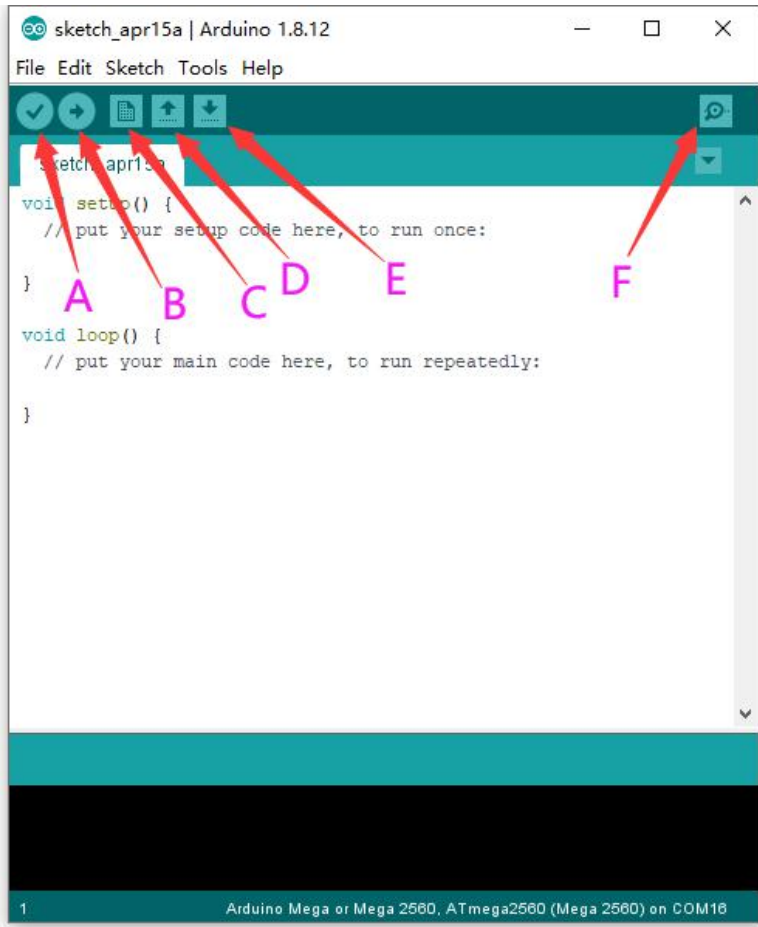


The screenshot shows the Arduino IDE interface with the 'Tools' menu open. The 'Tools' menu is highlighted with a red box. The 'Port: "COM16"' option is selected and highlighted with a blue background, also enclosed in a red box. A sub-menu titled 'Serial ports' is visible to the right of the 'Port' option, with 'COM16' selected and checked, also enclosed in a red box. The IDE window title is 'sketch_apr15a | Arduino 1.8.12'. The code editor shows the following code:

```
sketch_apr15a
void setup() {
  // put your
}

void loop() {
  // put your
}
```

At the bottom of the IDE, the status bar displays: '1 Arduino Mega or Mega 2560, ATmega2560 (Mega 2560) on COM16'.



A- Used to verify whether there is any compiling mistakes or not.

B- Used to upload the sketch to your Arduino board.

C- Used to create shortcut window of a new sketch.

D- Used to directly open an example sketch.

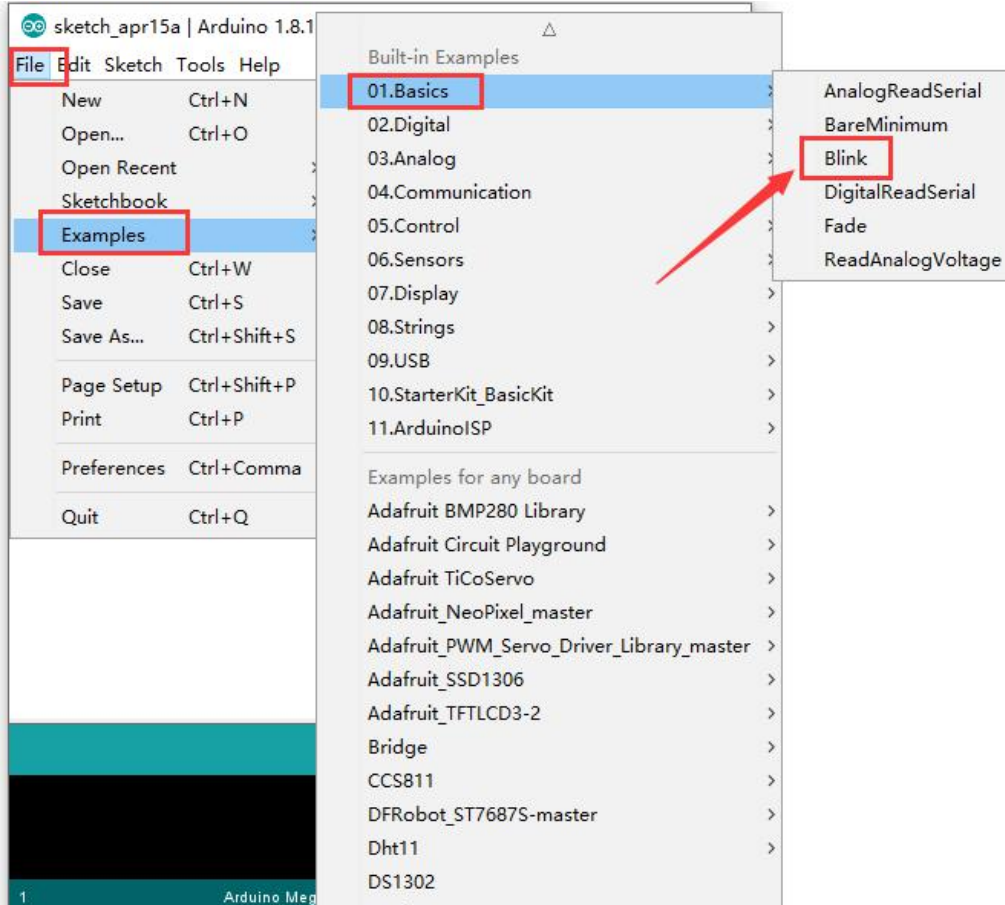
E- Used to save the sketch.

F- Used to send the serial data received from board to the serial monitor.



5.4 Start A Program

Open the file to select **Example**, and click **BASIC>BLINK**, as shown below:





```
Blink | Arduino 1.8.12
File Edit Sketch Tools Help

Blink
by Corby Newman

This example code is in the public domain.

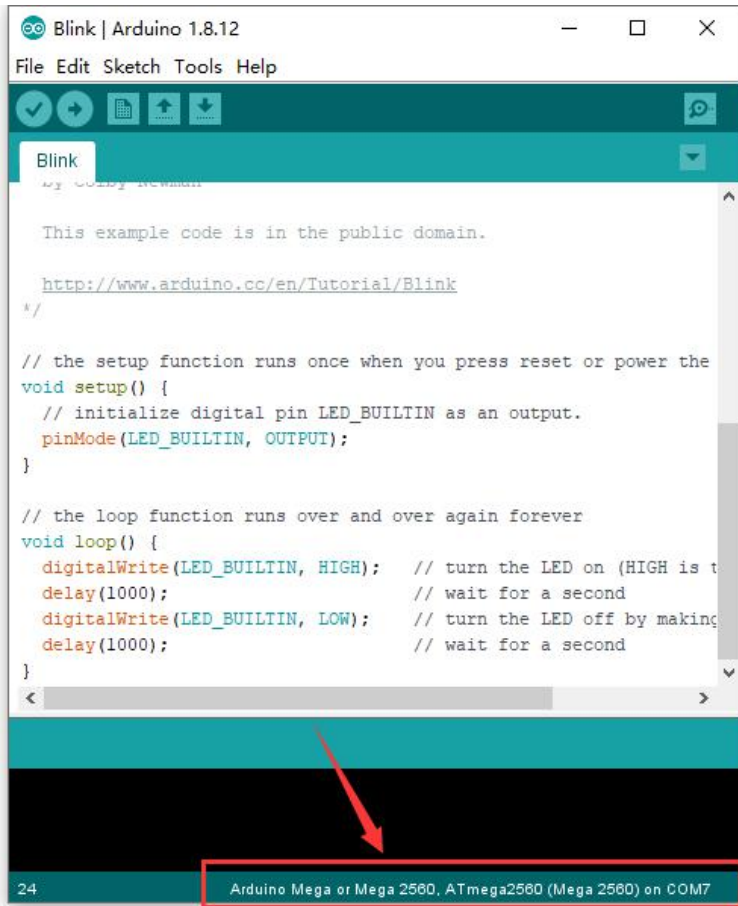
http://www.arduino.cc/en/Tutorial/Blink
*/


// the setup function runs once when you press reset or power the
void setup() {
  // initialize digital pin LED_BUILTIN as an output.
  pinMode(LED_BUILTIN, OUTPUT);
}

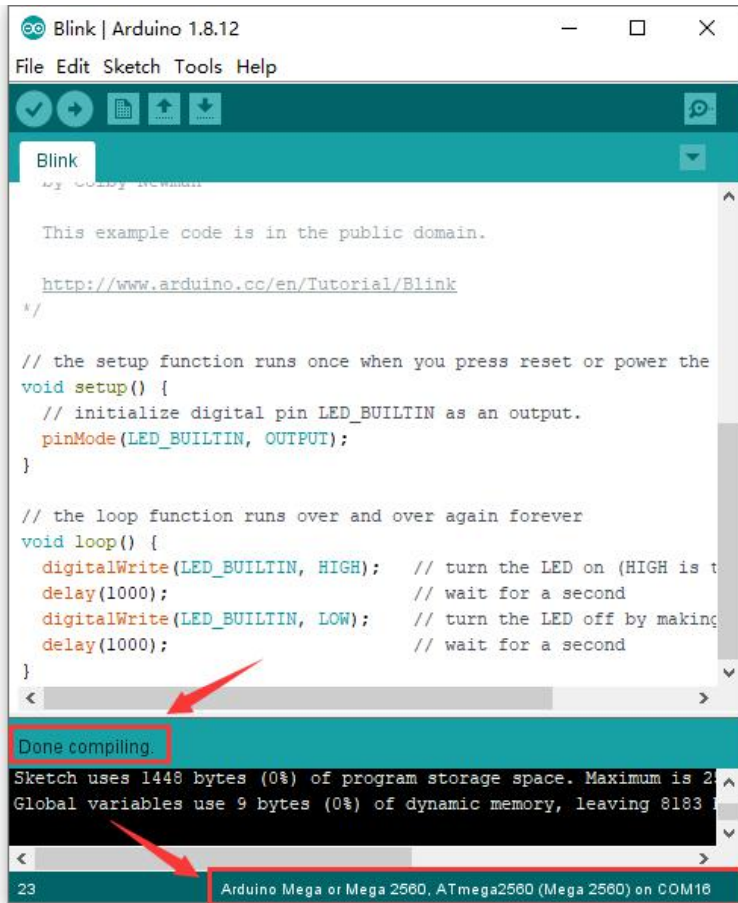
// the loop function runs over and over again forever
void loop() {
  digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the
  delay(1000); // wait for a second
  digitalWrite(LED_BUILTIN, LOW); // turn the LED off by making
  delay(1000); // wait for a second
}

23 Arduino Mega or Mega 2560, ATmega2560 (Mega 2560) on COM16
```

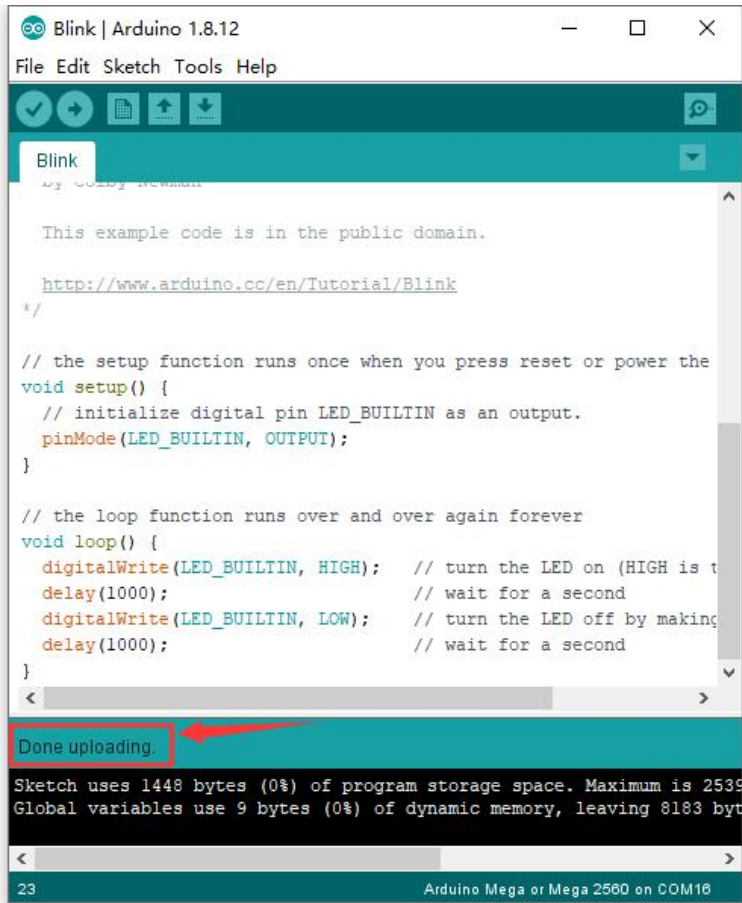
Set the correct **COM port**, and the corresponding board and COM port are shown on the lower right of IDE.



Click  to start compiling the program, and check errors.



Click  to upload the program



After the program is uploaded successfully, the onboard LED blinks. Congratulations, you finish the first program.

5. MAC System

5.1 Install Arduino IDE on MAC System

The installation instruction is as same as the chapter 4.1, as shown below:



ARDUINO 1.8.12

Arduino IDE that can be used with any Arduino board, including the Arduino Yún and Arduino DUE. Refer to the [Getting Started](#) page for Installation instructions.

[See the release notes.](#)

Windows Installer

Windows ZIP file for non admin install

Mac OS X 10.8 Mountain Lion or newer

Linux 32 bits

Linux 64 bits

Linux ARM 32

Linux ARM 64

[Source](#)



5.2 Download the Driver of CH340

<https://fs.keyestudio.com/CH340-MAC>

5.3 How to Install the Driver of CH340

[https://wiki.keyestudio.com/Download CH340 Driver on MAC System](https://wiki.keyestudio.com/Download_CH340_Driver_on_MAC_System)

5.4 Arduino IDE Setting

The setting method is as same as the chapter 4.3 except from COM port, as shown below.

