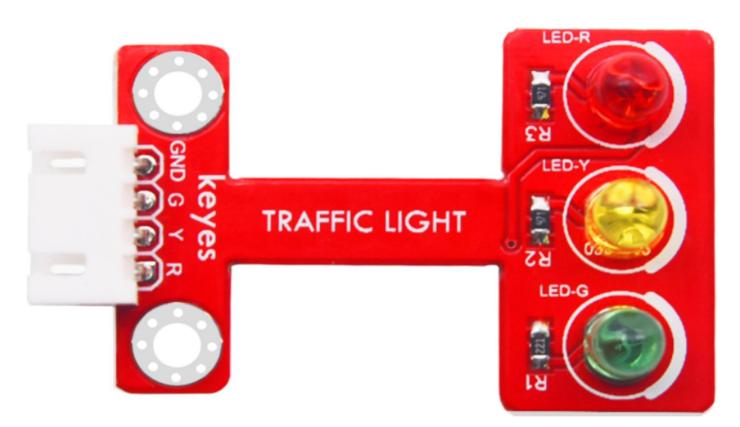
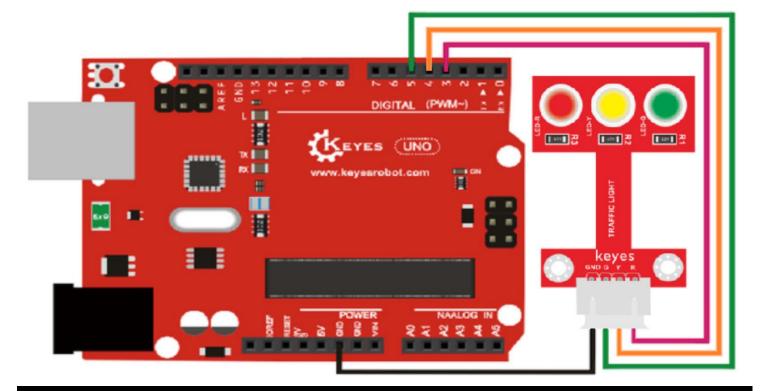


Shenzhen Keyi Interactive Robot Co., Ltd.

KE2056 KEYESLED traffic light module



Connection Diagram:



Guangdong ICP No. 14006164-2

https://www.keyesrobot.cn/



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Sample Code: int redled =3; // initialize digital pin 3. int yellowled =4; // initialize digital pin 4. int greenled =5; // initialize digital pin 5. void setup() { pinMode(redled, OUTPUT);// set the pin with red LED as "output" pinMode(yellowled, OUTPUT); // set the pin with yellow LED as "output" pinMode(greenled, OUTPUT); // set the pin with green LED as "output" } void loop() digitalWrite(greenled, HIGH);//// turn on green LED delay(5000);// wait 5 seconds digitalWrite(greenled, LOW); // turn off green LED for(int i=0;i<3;i++)// blinks for 3 times { delay(500);// wait 0.5 seconds digitalWrite(yellowled, HIGH);// turn on yellow LED delay(500);// wait 0.5 seconds digitalWrite(yellowled, LOW);// turn off yellow LED } delay(500);// wait 0.5 seconds digitalWrite(redled, HIGH);// turn on red LED delay(5000);// wait 5 seconds digitalWrite(redled, LOW);// turn off red LED }

Result:

Powered up and done uploading the code to the board, red, green and yellow LEDs on the module will automatically simulate the traffic light on and off.