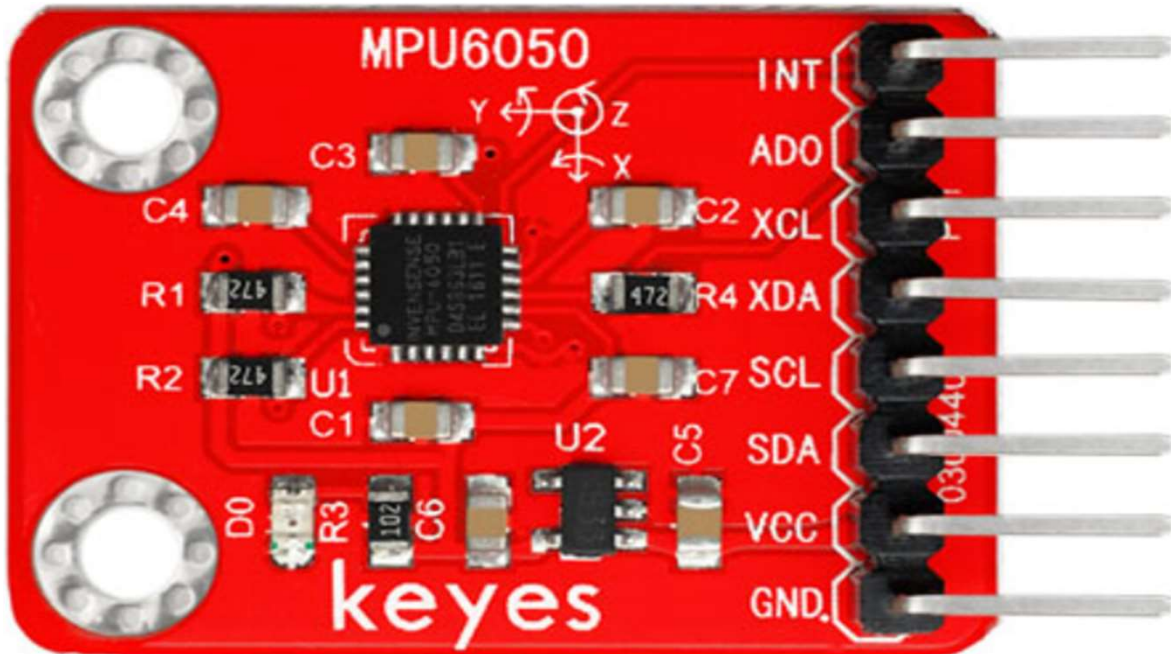


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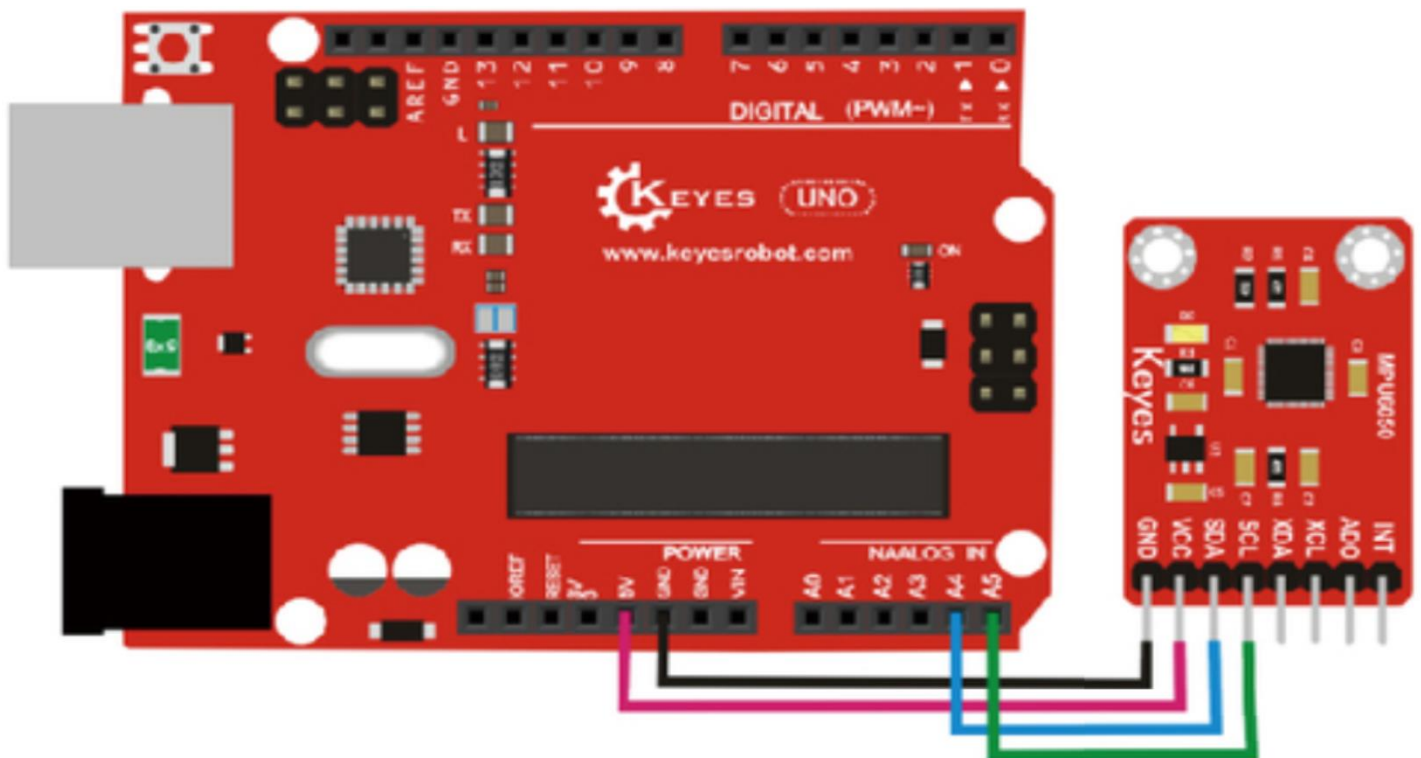
## KE0075 KEYES MPU6050 module three-dimensional angle sensor three-axis accelerometer electronic gyroscope

### Parameters:

Working Voltage: 3.3 ~ 5VDC  
 range of  $\pm 250$ ,  $\pm 500$ ,  $\pm 1000$ , and  $\pm 2000^\circ/\text{sec}$  (dps)  
 Colour: Red  
 Size: 34x22x12mm.



### PINOUT Instruction:



### Sample Code:

```
/*
  AnalogReadSerial
  Reads an analog input on pin 0, prints the result to the serial monitor.
  Attach the center pin of a potentiometer to pin A0, and the outside pins to +5V and ground.
  This example code is in the public domain.
*/
// the setup routine runs once when you press reset:
void setup() {
  // initialize serial communication at 9600 bits per second:
  Serial.begin(9600);
}

// the loop routine runs over and over again forever:
void loop() {
  // read the input on analog pin 0:
  int sensorValue = analogRead(A0);
  // print out the value you read:
  Serial.println(sensorValue);
  delay(1);    // delay in between reads for stability
}
```

### Result:

Open the Serial monitor and tilt the sensor in different direction and see the output values changing